EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S1	7	deichmann and clausen near tais	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:29
S2	7	Deichmann near Nikolaj	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:31
S3	7	clausen near tais	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:31
S4	2990	calibrat$3 near5 scanner$3	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:32
S5	0	S4 and calibrat$3 near object and calibrat$3 near2 camera and tsai and activat$3 near4 laser	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:33
S6	7	S4 and calibrat$3 near object and calibrat$3 near2 camera and tsai	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:33
S7	0	S4 and calibrat$3 near object and activat$3 and tsai	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:35
S8	4	S4 and calibrat$3 near object and visible and tsai	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:35

S9	2	calibrat$3 near object and calibrat$3 near2 camera and tsai and activat$3 near4 laser	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:36
S10	5	calibrat$3 near object and calibrat$3 near2 camera and tsai and laser near5 visible	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:38
S11	25	calibrat$3 near object and calibrat$3 near2 camera and tsai and laser and (orientat$3 and position)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:40
S12	5	calibrat$3 near object and calibrat$3 near2 camera and tsai and laser with (orientat$3 and position)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:40
S13	36	calibrat$3 near object and calibrat$3 near2 camera and tsai and (orientat$3 and position)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:42
S14	40	calibrat$3 near object and tsai and (orientat$3 and position)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:46
S15	0	calibrat$3 near object and tsai and (orientat$3 and position) near6 (three near dimemsional)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:48
S16	0	calibrat$3 near object and tsai and (orientat$3 and position) near6 (three-dimemsional)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:48

S17	0	calibrat$3 near object and (orientat $3 and position) near6 (three-dimemsional)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:48
S18	728	calibrat$3 near object and (orientat $3 and position)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:49
S19	233	calibrat$3 near object and (orientat $3 and position) near5 object	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:49
S20	82	calibrat$3 near object and (orientat $3 and position) near5 (object and camera)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:49
S21	13	S20 and tsai	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:49
S22	5	(calibrat$3 near object) near6 (two near plan$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:51
S23	59	(calibrat$3 near object) near6 (three near dimensional)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:52
S24	40	S23 and angle$3	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:52
S25	11	calibrat$3 near object and angle$3 near5 (two near plane)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 15:01

| S26 | 11 | calibrat$3 near object and angle$3 near5 (two near plane$3) | US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB | OR | ON | 2008/12/03 15:01 |

12/3/08 4:49:36 PM